

CSc 360

Operating Systems

Process Synchronization

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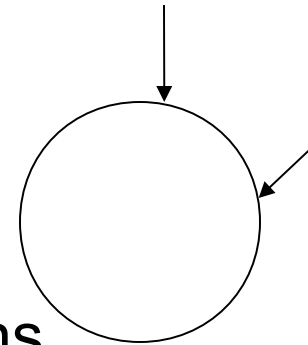
Summer 2015

The need for synchronization

- Multi-programming
 - multi-process
 - process communication
 - shared memory or message passing
 - multi-thread
- CPU scheduling
- Cooperating processes/threads
 - e.g., the “producer-consumer” problem
 - cannot consume the things not produced yet

The producer-consumer problem

- Solutions so far
 - bounded buffer
 - in, out variables; full, empty conditions
 - N buffer space, N-1 utilized at most
 - first-in-first-out queue
 - FIFO variable
- A simpler solution
 - to fully utilize the circular buffer
 - use a “counter” variable



The “counter” solution

```
while (true) {  
    /* produce an item and put in nextProduced */  
    while (count == BUFFER_SIZE) ; // do nothing  
    buffer [in] = nextProduced;  
    in = (in + 1) % BUFFER_SIZE;  
    count++;  
}
```

Producer

```
while (true) {  
    while (count == 0) ; // do nothing  
    nextConsumed = buffer[out];  
    out = (out + 1) % BUFFER_SIZE;  
    count--;  
    /* consume the item in nextConsumed */  
}
```

Consumer

Race condition

- E.g., increment a counter (shared variable)
 - read the counter (from memory)
 - increment by one (at CPU)
 - write the counter
- How about two threads?
 - *sharing* only one counter e.g., counter=5 initially
 - non-deterministic result: $R_1W_1R_2W_2$; $R_1R_2W_1W_2$
- “There is something not to be (always) shared”

Critical section

- Critical section
 - code section accessing shared data
 - only one thread executing in critical section
 - only one thread accessing the shared data: serialize
 - choose the right (size of) critical section!
- Approach: exclusion (lock)
 - if locked, wait!
 - if not lock, lock (and later, unlock)

Properties of “solutions”

- Mutual exclusion
 - no more than one process in the critical section
- Making process
 - if no process in the critical section, one can in
- Bounded waiting
 - for processes that want to get in the critical section, their waiting time is bounded

Problem formulation

- Only 2 processes, P_0 and P_1
- General structure of process P_i (other process P_j)
 do {
 entry section
 critical section
 exit section
 remainder section
 } **while** (1);
- Processes may **share** some common variables to synchronize their actions
 - do not get into the loop!

Algorithm 1

- Shared variables
 - `int turn;` // initially **turn = 0**
 - `turn == i`: P_i can enter its critical section
- Process P_i
 - do** {
 - while** (**turn != i**) ; // wait
 - critical section
 - turn = j;**
 - remainder section
 - } while (1);**
- Fate on other's hands: any problems?

Algorithm 2

- Shared variables
 - **boolean flag[2];**
initially **flag [0] = flag [1] = false.**
 - **flag [i] = true** : P_i ready to enter its critical section
- Process P_i
 - do {
 - flag[i] := true;**
 - while (flag[j]) ;**
critical section
 - flag [i] = false;**
remainder section
 - } while (1);**
- Fight for access: any problems?



Dekker's solution

- Combined shared variables of Algorithms 1 and 2
- Process P_i

```
while (true) {
    flag[i] = true;
    while (flag[j]) {
        if (turn == j) {
            flag[i] = false;
            while (turn == j);    // wait
            flag[i] = true;
        }
    }
    /* critical section */
    turn = j;
    flag[i] = false;
    /* remainder section */
}
```

- Be polite: meet all three requirements; solve the critical-section problem for **two** processes

Peterson's solution

- A simpler solution
 - combined shared variables of Algorithms 1 and 2
- Process P_i

```
do {  
    flag [i] := true;  
    turn = i;  
    while (flag [j] and turn == j) ; // wait  
    /* critical section */  
    flag [i] = false;  
    /* remainder section */  
} while (1);
```
- Meet all three requirements; solve the critical-section problem for **two** processes

This lecture

- Process synchronization
 - the producer-consumer problem
 - software solution for 2 processes
 - Peterson's solution
- Explore further
 - Lamport's bakery algorithm
 - for n processes
 - it's time to google!

Next lecture

- Process synchronization
 - other alternatives (read OSC7Ch6)